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| #include <Position.h>  #include <Arduino.h>  #include <Wifi.h>  #include <TinyGPS++.h>  #include <SoftwareSerial.h>  Position position(13);  void setup()  {  }  void loop()  {  position.dot(); position.dot(); position.dot();  position.dash(); position.dash(); position.dash();  position.dot(); position.dot(); position.dot();  delay(3000);  } | #ifndef position \_h  #define position \_h  #include <Arduino.h>  class Position  {  public:  Position(int pin);  void dot();  void dash();  private:  int \_pin;  };    #endif | #include <Arduino.h>  #include "Position.h"  Position:: Position (int pin)  {  pinMode(pin, OUTPUT);  \_pin = pin;  }  void Position::dot()  {  digitalWrite(\_pin, HIGH);  delay(250);  digitalWrite(\_pin, LOW);  delay(250);  }  void Position::dash()  {  digitalWrite(\_pin, HIGH);  delay(1000);  digitalWrite(\_pin, LOW);  delay(250);  } |